

Errata to First Printing  
*Fundamentals of Polarimetric Remote Sensing*  
 John R. Schott  
 (2009) SPIE Press

Page	Location	Recommended Change
21 + 22	Equation 3.1 and 3.3	Change $\varepsilon_x$ to $\varepsilon_x(z, t, \lambda)$ and add units of [V/m] at the end
21 + 22	Equation 3.2 and 3.4	Change $\varepsilon_y$ to $\varepsilon_y(z, t, \lambda)$ and add units of [V/m] at the end
21	5 <sup>th</sup> line from bottom	Change “angular frequency” to “angular temporal frequency [rad/sec]”
21	5 <sup>th</sup> line from bottom	Change “v” to “ $v = c/\lambda$ ”
21	4 <sup>th</sup> line from bottom	Change “ $k = \omega/c$ ” to “ $k = \omega/c$ is the angular spatial frequency [rad/m]”
22	Figure 3.1	Add units on x and y axes of “[V/m]” and on z axis of “[m]”
22	Figure 3.1	Change “ $\varepsilon$ ” to “ $\boldsymbol{\varepsilon}$ ”
23	Figure 3.2	Change two “ $\emptyset$ ” symbols to “ $\phi$ ”
23	Line 3	Change “two sources” to “two secondary sources”
23	Line 4	Change “source 1” to “secondary source 1 (SS <sub>1</sub> )” and change “source 2” to “secondary source 2 (SS <sub>2</sub> )”
23–25	Equation 3.6, 3.7, 3.8, 3.9, and 3.11	Add units of [V/m] at the end
23	Figure 3.3	Change “S <sub>1</sub> ” to “SS <sub>1</sub> ” and change “S <sub>2</sub> ” to “SS <sub>2</sub> ” to eliminate confusion with Stokes parameters, and change “o” on screen to “o”
25	Equation 3.12	Change “ $= (\varepsilon_0^2/2) \cdot I_0$ ” to “ $= \varepsilon_0^2/2 = I_0$ ” and add units of [V <sup>2</sup> /m <sup>2</sup> ] at the end
25	Equation 3.14	Add units of [V <sup>2</sup> /m <sup>2</sup> ] at the end
25	2 <sup>nd</sup> line from bottom	Change “ $\Delta l = l_1 - l_2$ ” to “ $\Delta l = l_2 - l_1$ ”
25–26	Equations 3.15a, 3.15b, 3.16, 3.17	Add units of [m <sup>2</sup> ] at the end
26–27	Equations 3.18, 3.19, 3.22, 3.23	Add units of [m] at the end
27	Equation 3.25	add units of [V/m] at the end
27	Equation 3.26	add units of [V/m] at the end
27	2 <sup>nd</sup> line from bottom	Change “are the phases” to “are the constant phases”
29	Line 2	Change “an ellipse rotated through an angle” to “an ellipse with major axis oriented at an angle”
29	Lines 8 + 17	Change “(cf. Fig. 3.1)” to “(Fig. 3.1)” and change “(cf. Fig. 3.8)” to “(Fig. 3.8)”
29	Line 12	Change “in a single plane.” to “in a single plane (Fig. 3.8a).”
29	Last Line	Change “this convention” to “this convention (fixed-plane rotation as seen by the receiver)”
30	Line 1	Change “the opposite convention” to “the opposite convention (rotation as seen by the transmitter)”
31	Line 1 + 2	Change “orientation angle” to “field rotation angle” in 2 places
31	Equations 3.30a, 3.30b, 3.31a, 3.31b, and 3.32	Add units of [V/m] at the end
31	2 <sup>nd</sup> line from bottom	Change “ $\phi = \pi/2$ or $\phi = (3/2)\pi$ ” to “ $\phi = \pm\pi/2$ ”
32	Line 4	Change “ $\phi = (3/2)\pi$ ” to “ $\phi = -\pi/2$ ”

33 + 34	Equation 4.2 and 4.7	Add units of $[V^4/m^4]$ at the end
33–37	Equations 4.3 through 4.6, 4.10 through 4.23	Add units of $[V^2/m^2]$ at the end
34	Line 13	Change “yielding” to “yielding using the four-quadrant arctangent”
35	Line 4	Change “ $\phi = (3/2)\pi$ ” to “ $\phi = -\pi/2$ ”
40	Figure 4.2	Add $S_3 = 0$ to Pickering, Modified Pickering, and Fessenkov’s methods
40	Figure 4.2	Change Fessenkov’s method to $S_1 = (2/3) \cdot (2 \cdot E_{0^\circ} - E_{60^\circ} - E_{120^\circ})$ and $S_2 = -(2/\sqrt{3}) \cdot (E_{120^\circ} - E_{60^\circ})$
40	Table 4.1	Add line “ $S_0$ – Always – Never”
41	Figure 4.3 Caption	Change “Stokes Vectors” to “Common Normalized Stokes Vectors”
45	Figure 4.6 Caption	Change “ $y$ ” to “ $\psi$ ”
57	Figure 5.5	Change five “ $\emptyset$ ” symbols to “ $\phi$ ”
58	Equation 5.19	Change “ $T_{\emptyset}$ ” to “ $T_{\phi}$ ” (i.e., 45° sloped line completely inside circle)
59 + 60	Equation 5.28 and 5.29a	Change “ $M_{\emptyset=90}$ ” to “ $M_{\phi=90}$ ”
65	Figure 6.2	Change “ $L(\theta_r, \phi_{r0})$ ” to “ $L(\theta_r, \phi_r)$ ”
67	Equation 6.6b	Make $f$ bold (i.e., $\mathbf{f}$ )
68	Equation 6.7	Add units of $[W/m^2/sr]$
68	Equation 6.8	Add units of $[W/m^2]$
75	3 <sup>rd</sup> line from bottom	Change “Coulson (1998)” to “Coulson (1988)”
85	Equation 6.25	Add arrow notation above $E$ Stokes vector
88	Equation 6.38g	Change to $f_{20} = 2 \otimes \emptyset - \otimes \otimes$
103	8 <sup>th</sup> reference	Remove redundant “Nadal, F.” author
111	Line 14+15	Change “an error term” to “a residual error term”
168	Line 8	Change “according to” to “according to the modified Pickering method”
169	Line 21	Change “[Gaskill (1979)]” to “[Gaskill (1978)]”
170	Figure 10.3 Caption	Change “BRFV” to “BRVF”
196	Figure 11.6 Caption	Change “of a GPS” to “of a GPS satellite vehicle”
200	Equation 11.3	Change $P(\ , \sigma, B)$ to $P(\theta_N, \sigma, B)$
245	Line 5 of Author’s Bio	Change “Unites States” to “United States”